

Mixed precision recursive block diagonalization for bivariate functions of matrices

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Univariate vs bivariate matrix functions

We may define **univariate** matrix functions in several ways, for $f(z) = \sum_{i \geq 0} f_i z^i$,

$$f(A)v = \sum_{i \geq 0} f_i A^i v = \frac{1}{2\pi i} \int_{\Gamma} f(z)(zI - A)^{-1} v \, dz.$$

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This can be generalized to the **bivariate** case, by setting for $f(z, w) = \sum_{i, j \geq 0} f_{ij} z^i w^j$:

$$f\{A, B^T\}(C) = \sum_{i, j \geq 0} f_{ij} A^i C B^j = -\frac{1}{4\pi^2} \int_{\Gamma_A} \int_{\Gamma_B} f(z, w)(zI - A)^{-1} C (zI - B^T)^{-1} \, dz \, dw.$$

- Most of the properties of univariate matrix functions carry over to this more general setting.
- **Similarities** on A, B behave well:

$$f\{A, B^T\}(C) = V \cdot f\{V^{-1}AV, (W^{-1}BW)^T\}(V^{-1}CW) \cdot W^{-1},$$

for any invertible matrices V, W .

Applications

- if X satisfies $AX + XB = C$, then

$$C = f\{A, B^T\}(X), \quad f(x, y) = x + y,$$

and therefore the solution of a **Sylvester equation** is expressed as:

$$X = g\{A, B^T\}(C), \quad g(x, y) = \frac{1}{x + y}.$$

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- Similar ideas apply for **generalized Sylvester equations** of the form $p\{A, B^T\}(X) = C$, whose solution is expressed using $f(x, y) := \frac{1}{p(x, y)}$.
- $f\{A, A^T\}(H)$ is the **Fréchet derivative** of $g(z)$ at A in the direction H , if $f(z, w)$ is the divided difference of $g(z)$.
- There is a nice connection with **Kronecker sums**; if $\mathcal{A} = B^T \otimes I + I \otimes A$ then

$$\text{vec}(X) = f(\mathcal{A})(\text{vec}(C)), \implies X = g\{A, B^T\}(C), \quad g(x, y) = f(x + y).$$

Evaluation in the diagonalizable case

$$f(x, y) = \sum_{ij} f_{ij} x^i y^j \implies f\{A, B^T\}(C) = \sum_{ij} f_{ij} A^i C B^j.$$

When A, B are **diagonalizable**, i.e., $A = V_A D_A V_A^{-1}$ and $B = V_B D_B V_B^{-1}$:

$$\begin{aligned} f\{A, B^T\}(C) &= V_A \sum_{ij} f_{ij} D_A^i V_A^{-1} C V_B D_B^j V_B^{-1}, \\ &= V_A f\{D_A, D_B\}(V_A^{-1} C V_B) V_B^{-1}. \end{aligned}$$

Hence, we have (\circ is the Hadamard product):

$$f\{A, B^T\}(C) = V_A \left(\begin{bmatrix} f(\lambda_1, \mu_1) & \dots & f(\lambda_1, \mu_n) \\ \vdots & & \vdots \\ f(\lambda_m, \mu_1) & \dots & f(\lambda_m, \mu_n) \end{bmatrix} \circ V_A^{-1} C V_B \right) V_B^{-1}.$$

How do we compute $f\{A, B^T\}(C)$ for **generic functions** and **non-normal matrices**?

A bivariate evaluation scheme

Our aim: evaluating $f\{A, B^T\}(C)$.

- We can assume A, B triangular by taking **Schur forms**.
- We can partition the diagonal blocks of A, B so that their **spectra** are **separated**.
- We now need a formula for

$$F := f \left\{ \begin{bmatrix} A_{11} & A_{12} \\ & A_{22} \end{bmatrix}, \begin{bmatrix} B_{11} & B_{12} \\ & B_{22} \end{bmatrix}^T \right\} (C).$$

The generic case is then obtained by **divide-and-conquer**.

Block diagonalization

Let A, B be **block upper triangular**:

$$A = \begin{bmatrix} A_{11} & A_{12} \\ & A_{22} \end{bmatrix}, \quad B = \begin{bmatrix} B_{11} & B_{12} \\ & B_{22} \end{bmatrix}.$$

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If V, W verify $A_{11}V - A_{22}V = A_{12}$ and $B_{11}W - B_{22}W = B_{12}$, then:

$$\underbrace{\begin{bmatrix} I & V \\ & I \end{bmatrix}}_{\tilde{V}} A \begin{bmatrix} I & -V \\ & I \end{bmatrix} = \begin{bmatrix} A_{11} & \\ & A_{22} \end{bmatrix}, \quad \underbrace{\begin{bmatrix} I & W \\ & I \end{bmatrix}}_{\tilde{W}} B \begin{bmatrix} I & -W \\ & I \end{bmatrix} = \begin{bmatrix} B_{11} & \\ & B_{22} \end{bmatrix}.$$

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So that:

$$\begin{bmatrix} I & V \\ & I \end{bmatrix} f_{\{A, B^T\}}(C) \begin{bmatrix} I & -W \\ & I \end{bmatrix} = f \left\{ \underbrace{\begin{bmatrix} A_{11} & \\ & A_{22} \end{bmatrix}, \begin{bmatrix} B_{11}^T & \\ & B_{22}^T \end{bmatrix}}_{\text{decouple into 4 function evaluations of smaller matrices}} \right\} (\tilde{V} C \tilde{W}^{-1})$$

Algorithm 1 Evaluates $f\{A, B^T\}(C)$

1: **procedure** fun2m(f, A, B, C)
2: $[Q_A, T_A] = \text{schur}(A)$, $[Q_B, T_B] = \text{schur}(B)$
3: $\tilde{C} \leftarrow Q_A^* C Q_B$
4: $F \leftarrow \text{fun2m_rec}(f, T_A, T_B, \tilde{C})$
5: **return** $Q_A F Q_B^*$
6: **end procedure**

1: **procedure** fun2m_rec(f, A, B, C)
2: **if** A, B are small **then return** $f\{A, B^T\}(C)$
3: **else**
4: Partition A, B and C as:

$$A = \begin{bmatrix} A_{11} & A_{12} \\ & A_{22} \end{bmatrix}, \quad B = \begin{bmatrix} B_{11} & B_{12} \\ & B_{22} \end{bmatrix}, \quad C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$$

5: Retrieve V and W by solving Sylvester equations
6: Compute $\begin{bmatrix} \tilde{C}_{11} & \tilde{C}_{12} \\ \tilde{C}_{21} & \tilde{C}_{22} \end{bmatrix} = \begin{bmatrix} I & V \\ & I \end{bmatrix} \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} \begin{bmatrix} I & -W \\ & I \end{bmatrix}$
7: $F_{ij} \leftarrow \text{fun2m_rec}(f, A_{ii}, B_{jj}, \tilde{C}_{ij})$, for $i, j = 1, 2$
8: **return** $\begin{bmatrix} I & -V \\ & I \end{bmatrix} \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix} \begin{bmatrix} I & W \\ & I \end{bmatrix}$
9: **end if**
10: **end procedure**

Algorithm 2 Evaluates $f\{A, B^T\}(C)$

1: **procedure** fun2m(f, A, B, C)
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Blocking strategy

Each recursive call needs the matrices $\begin{bmatrix} I & V \\ & I \end{bmatrix}$, $\begin{bmatrix} I & W \\ & I \end{bmatrix}$ to be **not so ill-conditioned**. This is equivalent to keep under control the norm of the solutions of

$$A_{11}V - VA_{22} = A_{12}, \quad B_{11}W - WB_{22} = B_{12}.$$

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As in the **Schur-Parlett** algorithm [4], the blocking is based on **clustering the eigenvalues** of A (resp. B) such that, for a given $\delta > 0$:

- For each eigenvalue λ in a cluster $\exists \mu$ in the same cluster s.t. $|\lambda - \mu| \leq \delta$.
- Each pair of eig. λ, μ that belong to different clusters verifies $|\lambda - \mu| > \delta$

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- Each pair of eig. λ, μ that belong to different clusters verifies $|\lambda - \mu| > \delta$

Since this criterion is only heuristic, we also check a posteriori whether $\|V\|_2 > \gamma \|A_{12}\|$ (resp. $\|W\|_2 > \gamma \|B_{12}\|$) for a moderate $\gamma \geq \delta^{-1}$.

In that case **the two clusters are merged**.

[4] Davies, Higham. *A Schur-Parlett algorithm for computing matrix functions*. SIMAX, 2003.

Evaluating the function of the triangular atomic blocks

Core idea [5,6]: Consider small diagonal random perturbations E_A, E_B and compute

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- Lower the unit round-off to u^2 and compute $\tilde{A} = A + E_A, \tilde{B} = B + E_B$ with $\|E_A\| = u\|A\|, \|E_B\| = u\|B\|$.
- Set the unit round-off to $u_h \leq u$ and retrieve **triangular V_A, V_B** by solving shifted linear systems with \tilde{A} and \tilde{B} .
- Evaluate $V_A f\{D_A, D_B\} (V_A^{-1} C V_B) V_B^{-1}$ using u_h
- Go back to unit round-off u .

[5] Davies. *Approximate diagonalization*. SIMAX, 2008.

[6] Higham, Liu. *A multiprecision derivative-free Schur-Parlett algorithm for computing matrix functions*. MIMS EPrint 2020.19, 2020.

Choosing u_h

The following Lemma suggests the choice $u_h \leq \frac{u}{\kappa(V_A)\kappa(V_B)}$.

Lemma

Let $Y = V_A f\{D_A, D_B\} (V_A^{-1} C V_B) V_B^{-1}$, and let \hat{Y} be the corresponding quantity computed in floating point arithmetic. If the matrix multiplications are performed exactly, and $f(\lambda_i^A, \lambda_j^B)$ is computed with relative error bounded by u_h , then

$$\|F - \hat{F}\| \leq \kappa(V_A)\kappa(V_B)\|C\| \max_{i,j} |f(\lambda_i, \mu_j)| u_h.$$

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$\kappa(V_A)$ (analogously $\kappa(V_B)$) can be estimated from the entries of \tilde{A} :

$$\kappa(V_A) \lesssim m\zeta(\zeta + 1)^{m+1}, \quad \zeta = \frac{\max_{i < j} |\tilde{A}_{ij}|}{\min_{i \neq j} |\tilde{A}_{ii} - \tilde{A}_{jj}|} \quad (1)$$

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This is **usually too pessimistic**; practically, we apply the blocking method with a parameter $\delta_1 < \delta$ and we compute the maximum of (1) for the diagonal blocks.

Numerical results: highly non normal matrices

Setting

- $m = n = 64$, $f(x, y) = (x + y)^{-\frac{1}{2}}$.
- diag: diagonalization (no blocking and no HP).
- diag_hp: HP diagonalization (no blocking).
- Err: relative error with respect to $f\{A, B\}(C)$ evaluated with diag_hp using 128 digits.
- n_A, n_B : number of atomic blocks in A and B .
- κ_f : estimate of

$$\lim_{h \rightarrow 0} \sup_{\substack{\|\Delta A\| \\ \|A\|}, \substack{\|\Delta B\| \\ \|B\|} \leq h} \frac{\|f\{A + \Delta A, B^T + \Delta B^T\}(C) - f\{A, B^T\}(C)\|}{h}.$$

Test	FUN2M					DIAG		DIAG_HP			$\kappa_f \cdot u$
	Err	Time	nA	nB	Digits	Err	Time	Time	Err	Digits	
jordbloc	$2.0 \cdot 10^{-9}$	0.02	15	15	48	$3.9 \cdot 10^{-1}$	0.008	1.65	$2.0 \cdot 10^{-9}$	51	$3.2 \cdot 10^{-10}$
grcar	$1.5 \cdot 10^{-13}$	1.53	1	1	40	$7.7 \cdot 10^{-8}$	0.008	1.54	$1.5 \cdot 10^{-13}$	40	$1.0 \cdot 10^{-9}$
smoke	$3.5 \cdot 10^{-9}$	1.46	1	1	35	$1.1 \cdot 10^{-8}$	0.002	1.45	$1.8 \cdot 10^{-9}$	35	$5.0 \cdot 10^{-1}$
kahan	$3.4 \cdot 10^{-16}$	1.37	1	1	43	$6.8 \cdot 10^{-7}$	0.002	1.36	$4.5 \cdot 10^{-16}$	43	$1.4 \cdot 10^{-7}$
lesp	$4.4 \cdot 10^{-15}$	0.23	9	9	35	$1.6 \cdot 10^{-1}$	0.003	1.32	$3.5 \cdot 10^{-15}$	36	$1.9 \cdot 10^{-15}$
sampling	$1.0 \cdot 10^{-7}$	0.41	10	9	49	$2.2 \cdot 10^{-2}$	0.006	2.04	$1.0 \cdot 10^{-7}$	49	$8.2 \cdot 10^{-8}$
grcar-rand	$5.2 \cdot 10^{-12}$	0.39	1	16	29	$7.8 \cdot 10^{-8}$	0.009	1.45	$5.2 \cdot 10^{-12}$	31	$3.7 \cdot 10^{-6}$

Numerical results: random matrices

$$\text{Test} = \text{randn}, f(x, y) = \frac{1}{\sqrt{x+y}(x-y)}$$

Size	fun2m			diag
	Time	nA	nB	Time
64	0.01	16	16	0.01
128	0.08	32	32	0.06
256	0.27	64	64	0.2
512	1.42	128	128	1.07
1,024	5.47	256	256	4.09
2,048	29.12	512	512	22.01
4,096	243.41	1,024	1,024	132.48

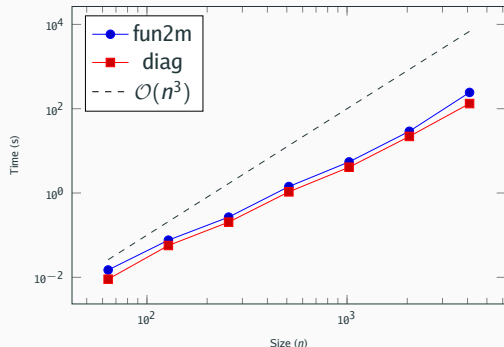


Figure 1: Timings of fun2m and diag for well-conditioned A and B .

Is there code available?

Yes, we have the Julia package BivMatFun.

```
julia> import Pkg;  
julia> Pkg.add(url = "https://github.com/numpi/BivMatFun.git");  
julia> using BivMatFun;
```

```
# Only complex matrices are implemented
```

```
julia> n = 1024;  
julia> A = complex(randn(n,n)); B = complex(randn(n,n));  
julia> C = complex(randn(n,n));  
julia> f = (z,w,i,j) -> 1 / (z + w);  
julia> X, _ = fun2m(f, A, B, C);  
julia> using LinearAlgebra;  
julia> opnorm(A*X + X*B - C) / opnorm(X)
```

3.277465131019034e-13

Conclusions

Reference:

- S. Massei., L. R. *Mixed precision recursive block diagonalization for bivariate functions of matrices*, to appear on SIMAX, 2022.

Remarks:

- A **perturb-and-diagonalize** approach combined with high precision can be a workaround when dealing with linear algebra tasks related to (nearly) non diagonalizable matrices.
- An effective **blocking** strategy is necessary in order to **mitigate the impact of high precision arithmetic** on timings.

Possible applications/extensions

- Projection methods for function of Kronecker sum structured matrices.
- Multivariate matrix functions \rightarrow operations on tensors.