

WS on Models, Algorithms and Methodologies for Hierarchical Parallelism in new HPC Systems

The High Performance Internet of Things: using GVirtuS for gluing cloud computing and ubiquitous connected devices





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Motivations

- This **preliminary** work is addressed to speculate about:
 - The next generation of
 "off the shelf Beowulf clusters"



 How to accelerate the Internet of Things component: High Performance Internet of Things



Generic Virtualization Service

(since March 2010)

- Framework for split-driver based abstraction components
- Plug-in architecture
- Independent from:
 - Hypervisor (or no-hypervisor)
 - Communication
 - Target of virtualization
 - Architecture!

• High performance:

- Enabling transparent virtualization
- With overall performances better or not too far from un-virtualized resources



Generic Virtualization Service

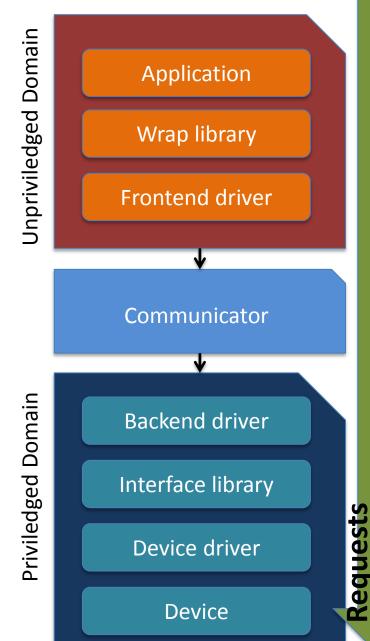
(since March 2010)

- From Google Scholar...
- A GPGPU transparent virtualization component for high performance computing clouds
- G Giunta, R Montella, G Agrillo, G Coviello Euro-Par 2010-Parallel Processing, 379-391
- A GPU Accelerated High Performance Cloud Computing Infrastructure for Grid Computing Based Virtual Environmental Luboratory G Giunta, R Montella, G Laccetti, Misaila, JG Blas
- Virtualizing general purpose GPUs for high trees mance cloud computing: an application to a full simulator
- R Di Lauro, F Giamone, L Ambrosica R (Colella Parallel and Distributed Processica Alb Colettions (ISPA), 2012 IEE
- A general-purpose virtualization service for HPC on cloud computing: an application to GPUs R Montella, G Coniello, G Giunta, G Laccetta, F Isaila, JG Blas Parallel Processing and Applied Mathematics, 740-749
- SlaaS-Sensing Incrument as a Service Using Cloud Computing to Turn Physical Instrument into Ubiquitous Service
- R Di Lauro, F Lucarelli, R Montella Parallel and Distributed Processing with Applications (ISPA), 2012 IEEE 10th ...

http://osl.uniparthenope.it/projects/gvirtus

Split-Driver approach

- Split-Driver
 - Hardware access by privileged domain.
 - Unprivileged domains access the device using a frontend/backend approach
- Frontend (FE):
 - Guest-side software component.
 - Stub: redirect requests to the backend.
- Backend (BE):
 - Manage device requests.
 - Device multiplexing.

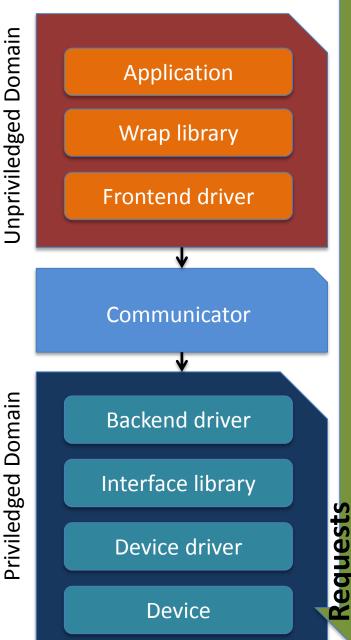


GVirtuS approach

- **GVirtuS Frontend**
 - Dynamic loadable library
 - Same application binary interface
 - Run on guest user space

Domain **Jnpriviledged**

- **GVirtuS Backend**
 - Server application
 - Run in host user space
 - **Concurrent requests**



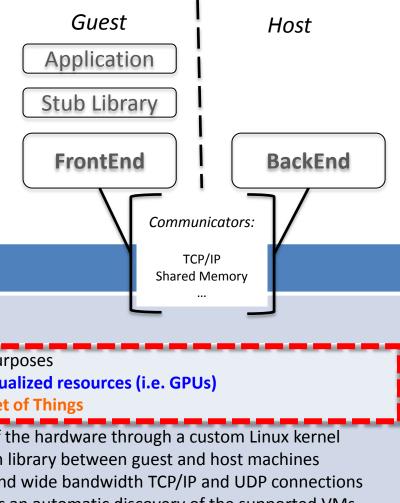
The Communicator

FE/BE comm

Hypervisor

- Provides a high performance communication between virtual machines and their hosts.
- The choice of the hypervisor deeply affects the efficiency of the communication.

Notes



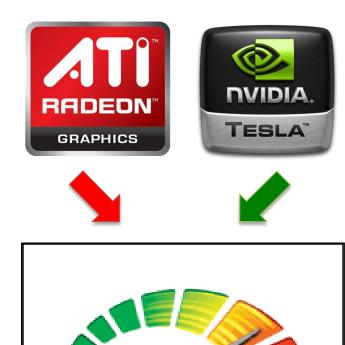
No hypervisor	Unix Sockets	Used for testing purposes	
Generic	TCP/IP	 Communication testing purposes Remote / Distributed virtualized resources (i.e. GPUs) High Performance Internet of Things 	
Xen	XenLoop	 runs directly on the top of the hardware through a custom Linux kernel provides a communication library between guest and host machines implements low latency and wide bandwidth TCP/IP and UDP connections app transparent and offers an automatic discovery of the supported VMs 	
VMware	Virtual Machine Communication Interface (VMCI)	 commercial hypervisor running at the application level provides a datagram API to exchange small messages a shared memory API to share data an access control API to control which resources a virtual machine can access and a discovery service for publishing and retrieving resources 	
KVM/QEMU	VMchannel	 Linux loadable kernel module now embedded as a standard component supplies a high performance guest/host communication based on a shared memory approach 	

An application: Virtualizing GPUs

• GPUs

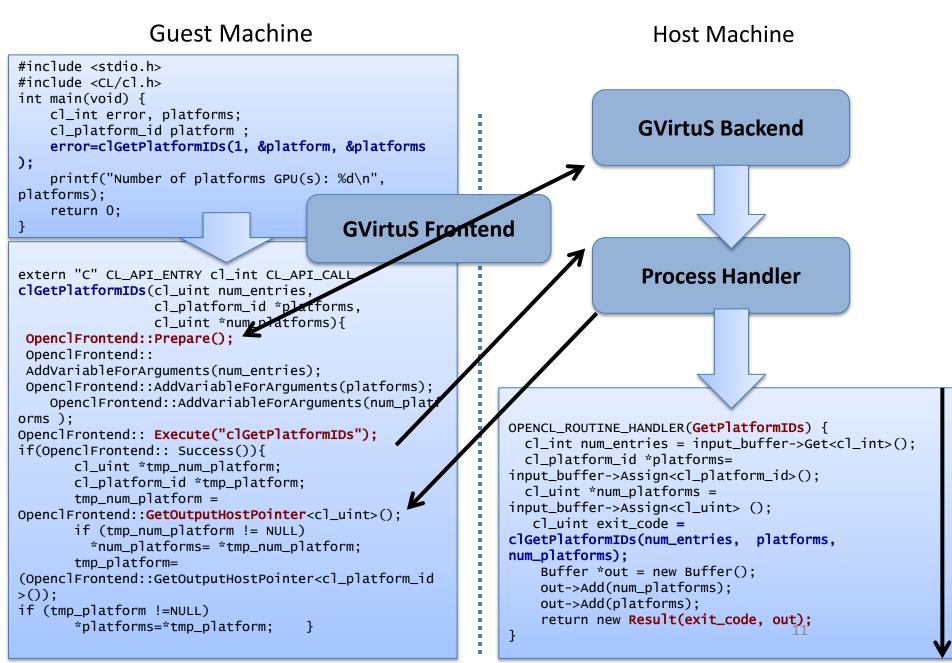
- Hypervisor independent
- Communicator independent
- GPU independent

The host plus a collection of devices managed by the OpenCL framework that allow an application to share resources and execute kernels on devices in the platform.



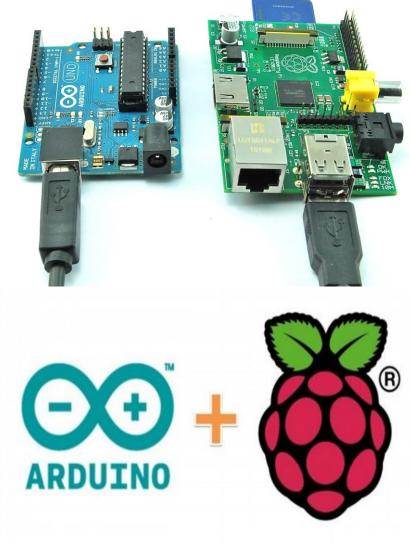


GVirtuS – libOpenCL.so



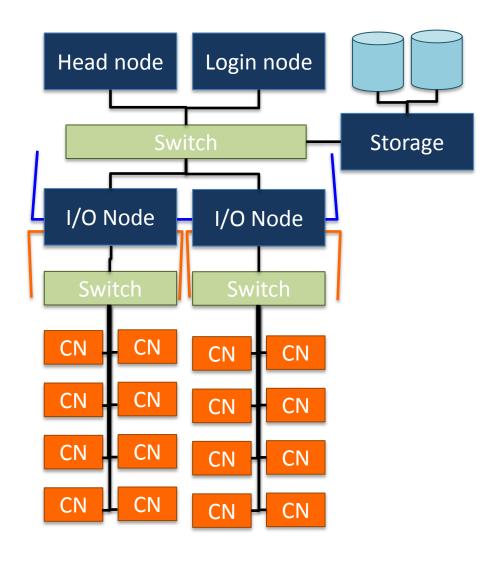
Accelerating ARM boards

- High Performance Computing will be ARM based
 - Cheaper and powerful
 - Low heat emission
 - High developable
- High Performance Internet of Things
 - Small and smart devices highly pervasive

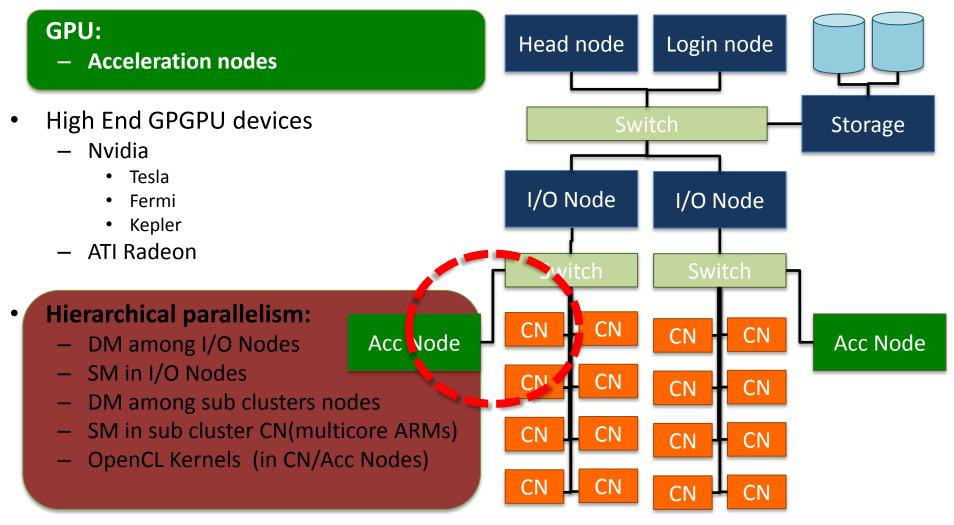


Figuring out the next generation HPC

- x86_64:
 - Head node
 - Login nodes
 - I/O nodes
 - Computing nodes for the cluster
 - I/O nodes for sub clusters
- ARM:
 - Computing nodes as multicore sub clusters



Enhancing the next generation of [low cost/middle end] HPC



NB: In this scenario we have ARM boards with a low performance GPU useless for HPC jobs

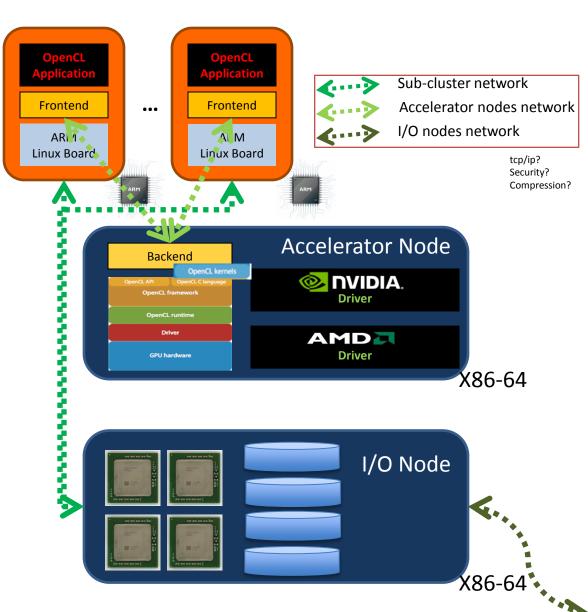
Distributed GPUs

Highlights:

- Using the Tcp/Ip Communicator FE/BE could be on different machines.
- ARM machines can access remote GPUs.

Applications:

- GPU for embedded systems as network machines
- Next generation of High Performance [Cloud] Computing



Prototyping

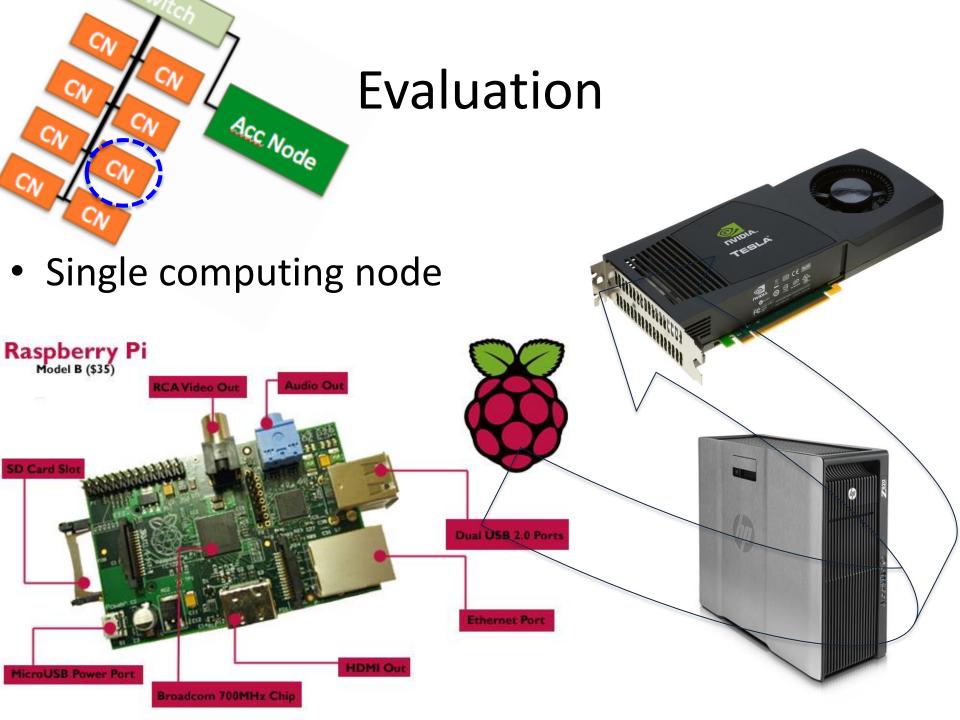
- Computing node:
 - Raspberry Pi mod. B. rev. 2
 - Wheezy Raspbian Linux
- Acceleration:
 - Genesis GE-i940 Tesla
 - i7-940 2,93 133 GHz fsb, Quad Core hyperthreaded 8 Mb cache CPU and 12Gb RAM.
 - 1 nVIDIA Quadro FX5800 4Gb RAM video card
 - 2 nVIDIA Tesla C1060 4 Gb RAM
- I/O:
 - Intel Xeon quad core HT
 - Ubuntu Linux 64bit



Tesla C1060 Computing Processor

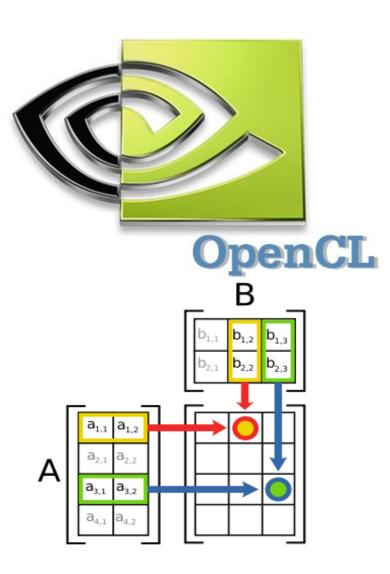


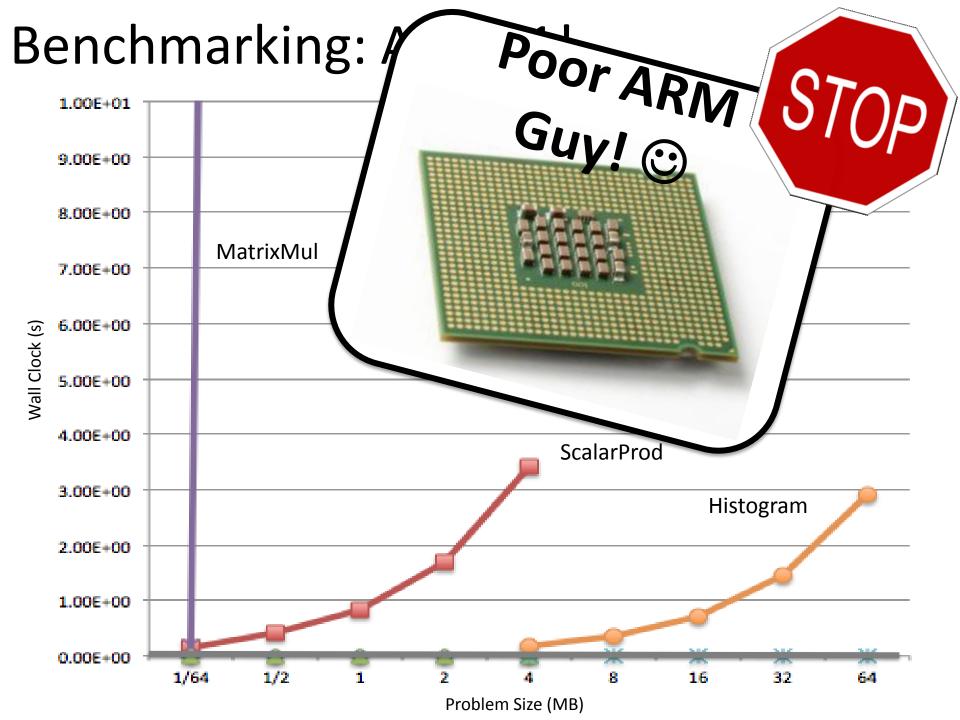
	Processor	1 x Tesla T10
	Number of cores	240
- 6	Core Clock	1.33 GHz
Ør.	On-board memory	4.0 GB
TEAL	Memory bandwidth	102 GB/sec peak
and the second	Memory I/O	512-bit, 800MHz GDDR3
-sil	Form factor	Full ATX: 4.736" (H) x 10.5" (L) Dual slot wide
	System I/O	PCle x16 Gen2
	Typical power	160 W



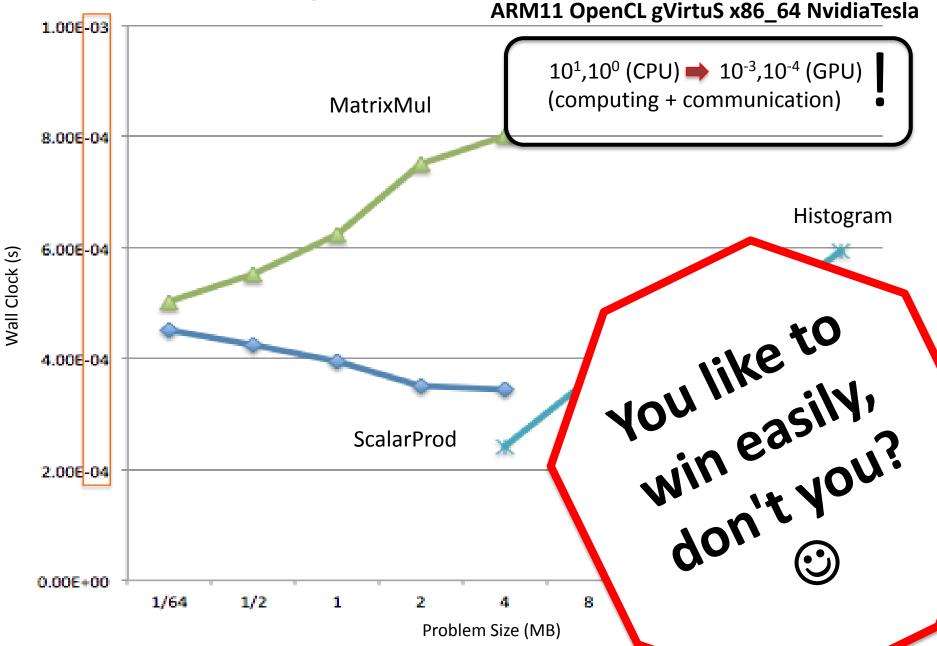
...from (NVIDIA) OpenCL SDK...

- ScalarProd computes k scalar products of two real vectors of length m.
 - Notice that each product is executed by an OpenCL thread on the GPU.
 - No synchronization is required.
- MatrixMul computes a matrix multiplication.
 - The matrices are mxn and nxp, respectively.
 - It partitions the input matrices in blocks and associates an OpenCL thread to each block.
 - No need of synchronization.
- **Histogram** returns the histogram of a set of *m* uniformly distributed real random numbers in 64 bins.
 - The set is distributed among the OpenCL threads each computing a local histogram.
 - The final result is obtained through synchronization and reduction techniques.

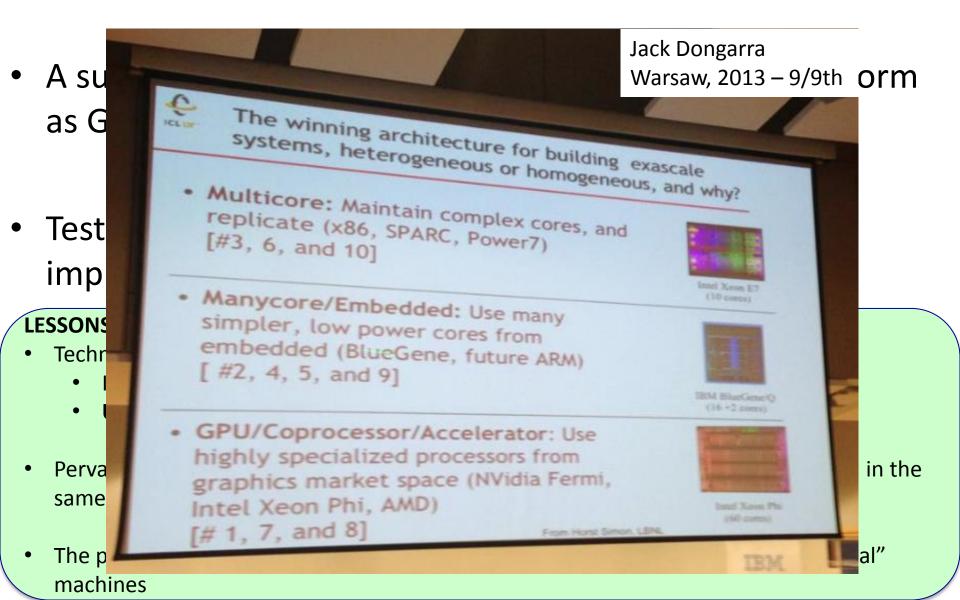




Benchmarking: GPU!



Conclusions and Future Works



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- More evaluation
- Multiple computing nodes





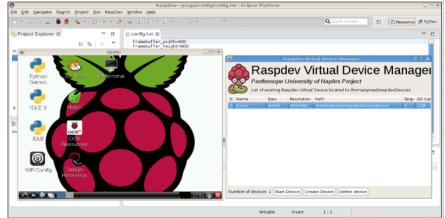
Conclusions and Future Works

- Repeat testing on better ARM board(s) i.e.
 - Quad Core CPU 1.2 GHz
 - 1 GB RAM
 - Giga Ethernet



http://web.uniparthenope.it/raspdev/

- Full OpenCL porting
- Application framework for the ARM "sub cluster" support
- Development of a comfortable SDK for hybrid programming



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Thank You!

http://osl.uniparthenope.it/projects/gvirtus/