A Distributed Hash Table for Shared Memory

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- 2 Contribution 1: Resolving Hash Collisions
- **3** Contribution 2: Hiding Latency
- 4 Experimental Evaluation
- 5 Conclusion

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Main challenge

Building a fast and CPU-efficient shared hash table:

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- Cheaper scalability
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Specialized algorithms and data structures needed!

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Contribution: Reducing roundtrips *while* CPU-efficient

Infiniband hardware

Specialized hardware used to construct high-performance networks:

- Comparable in price to Ethernet
- Supports bandwidths up to 100 Gb/s
- Direct access to memory via PCI-E bus

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RDMA: Remote Direct Memory Access

Directly access to remote memory without invoking remote CPUs

- Zero-copy networking
- Kernel bypassing
- No participation from remote CPUs

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Performance: one-sided RDMA vs TCP

Roundtrips latency: $< 3\mu s$ (Infiniband) vs $60\mu s$ (traditional Ethernet)

Hash Table: Challenges

Notation: Hash table

- $\mathcal{T} = \langle b_0, \dots, b_{n-1} \rangle$ as a sequence of buckets b_i , where:
 - *n* the hash table size and *m* the number of used entries
 - $\alpha = \frac{m}{n}$ the load factor

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Operation: *only* find-or-put(*d*)

Takes a data element d as parameter, and:

- if $d \in T$, return found
- if $d \notin T$, insert d and return **inserted**
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Design: Challenges

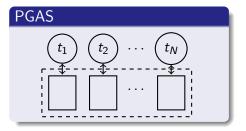
- How to *distribute* and access $T = \langle b_0, \ldots, b_{n-1} \rangle$ efficiently?
- How to design find-or-put to perform efficiently?

PGAS: Partitioned Global Address Space

Details

Assuming N participating threads:

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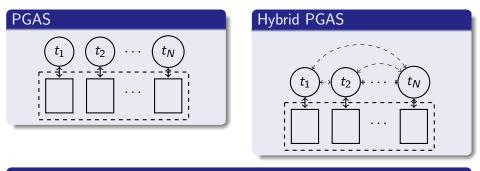


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Assuming N participating threads:

■ **PGAS:** shared + distributed memory model

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- PGAS: shared + distributed memory model
- Hybrid PGAS: PGAS + message passing (dashed edges)

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Efficiency: Resolving Hash Collisions

Occurs when h(x) = h(y) for data elements $x \neq y$

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- Pilaf, 2014 (Cuckoo)
- Nessie, 2014 (Cuckoo)
- FaRM, 2014 (Hopscotch)
- HERD, 2014 (CPU-intensive)

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- Require *locking* schemes
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Best strategy for find-or-put

Which strategy requires the least number of roundtrips?

Chained Hashing

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- Dynamic mem. management
- Storing pointers

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Linear Probing versus Hopscotch

- Due to Hopscotch invariant, lookups *may* be more expensive, but
- Inserts are arguably cheaper (amortized complexity)

Knuth, 1997

The *expected* number of buckets to examine until the intended buckets is found is *at most*:

$$\frac{1}{2}\Big(1+\frac{1}{(1-\alpha)^2}\Big)$$

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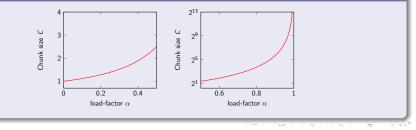
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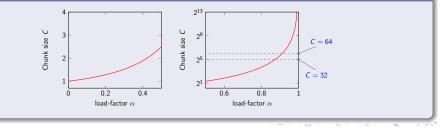
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Contribution: Asynchronous queries

Before chunk iteration, first request the next chunk:

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Defining query-chunk(i, d)

Obtains the *i*-th chunk, starting from bucket $b_{h(d)}$

Returns a handle s

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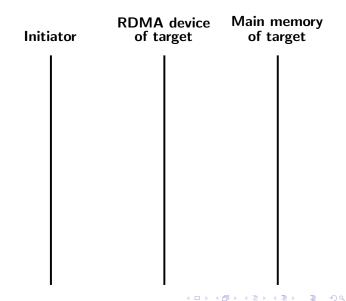
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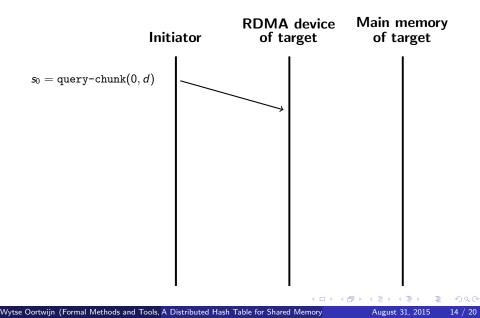
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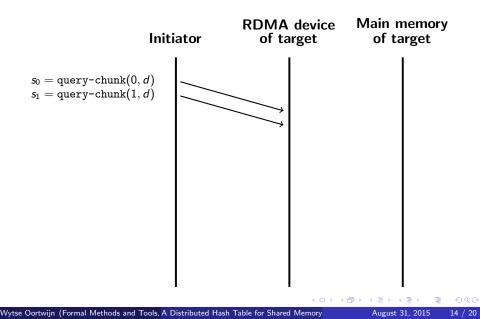
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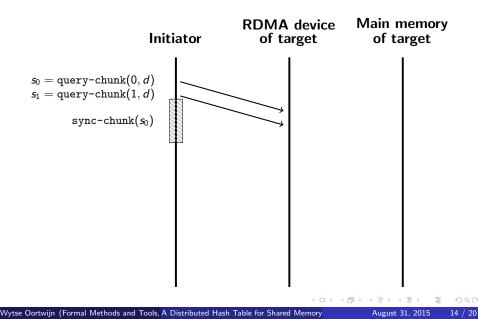
Defining sync-chunk(s)

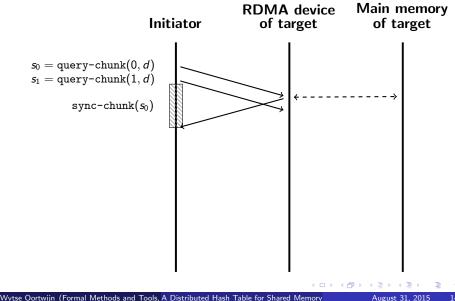
Takes a handle *s* as parameter, waits until the *corresponding* query has been completed.



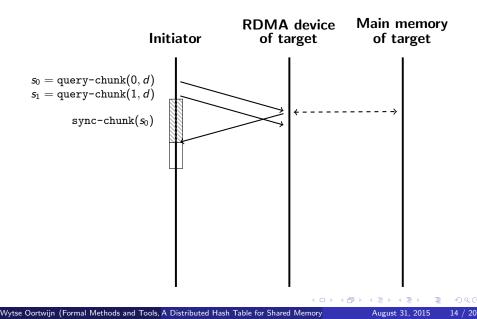


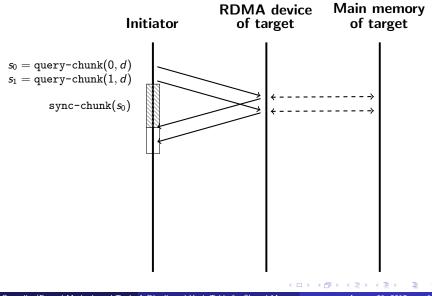


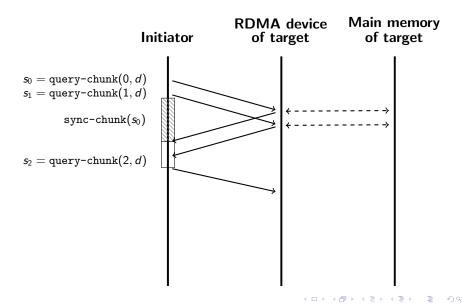


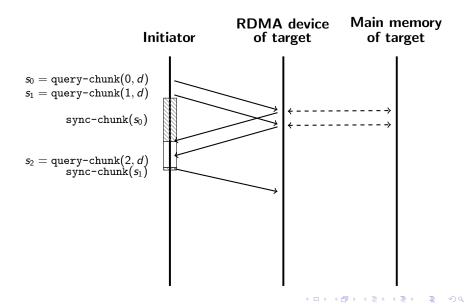


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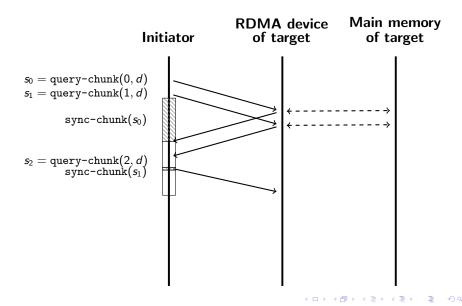




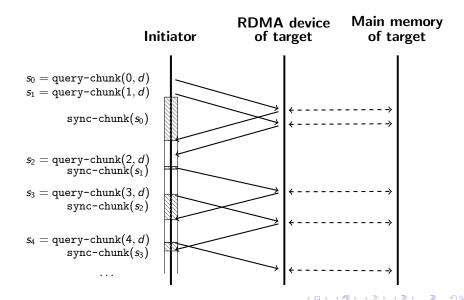




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Experimental Setup

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- 16 cores each (Intel E5-2630v3)
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- connected via 48Gb/s Infiniband

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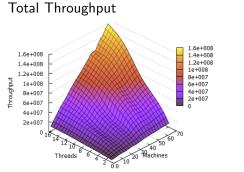
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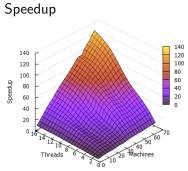
Benchmarks

Under different workloads, we measured:

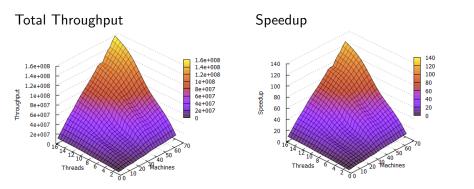
- Throughput of find-or-put
- Latency of find-or-put
- Roundtrips of find-or-put

Hash Table: Throughput





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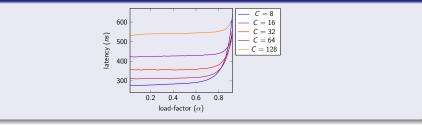


Observations

- Throughputs up to 140 × 10⁶ reached (66 machines)
- Remote speedup up to 110 obtained
- Local throughput of $495 imes 10^6$ reached (1 threads)

Hash Table: Latency

Local latency



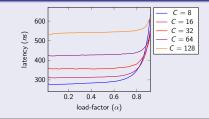
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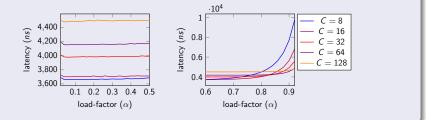
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Remote latency



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- Overlapping queries reduces waiting-times and decreases latency
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- \blacksquare Peak-throughput of 140×10^{6} op/s obtained

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Performance Indication

- **FaRM**: Inserts take $\sim 35 \mu s$
- **Pilaf**: Operations take $\sim 30 \mu s$
- **Nessie**: Inserts take $\sim 25 \mu s$

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